

Od neuronu do sieci: modelowanie układu nerwowego

**Ośrodkowe generatory wzorców (CPG)
jako przykłady małych sieci neuronalnych**

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na podstawie „The Book of GENESIS”

- Wzorce aktywności mięśniowej: chodzenie, pływanie, latanie, oddychanie, żucie, drapanie
- Przykłady:
 - pływanie uciekającego mięczaka *Tritonia diomedea*
 - rytmy trawienne homara *Panulirus interruptus* i kraba *Cancer borealis*
 - faliste ruchy pływne ryby i minoga
 - kroki karalucha
 - szybki ruch skrzydeł szarańczy w locie
 - skomplikowana lokomocja czworonoga

Tritonia Diomedea

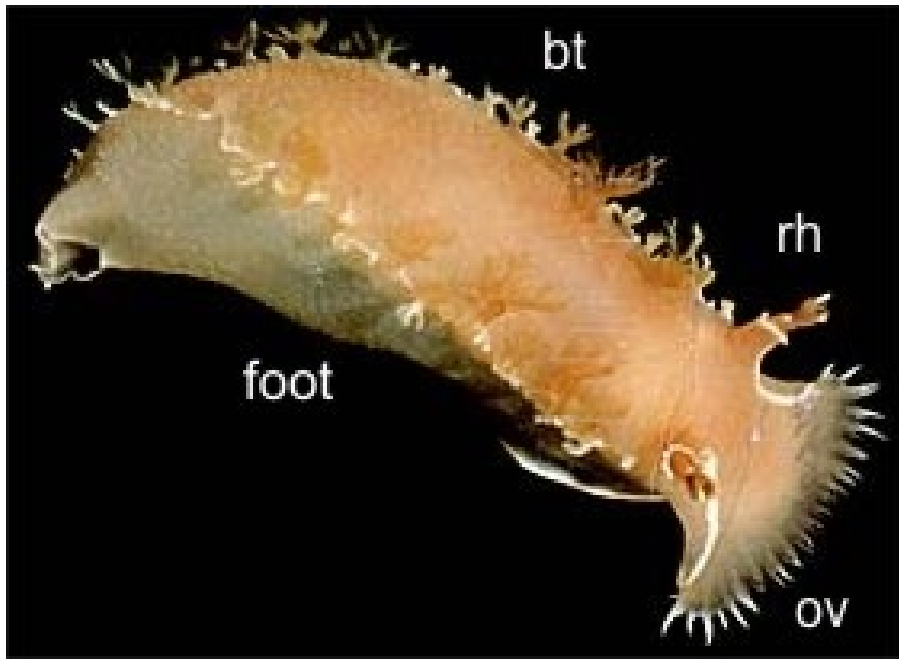


Photo of Tritonia diomedea.
Anterior is to the right.
bt = Branchial Tufts,
rh = Rhinophore,
ov = Oral Veil.

Następna strona: Tritonia escape swimming. The picture shows a Tritonia escaping from a sea star, Pycnopodia. At the top are simultaneous intracellular electrophysiological recordings from the 3 CPG neurons: C2, DSI, and VSI taken from an isolated brain. At the arrow, a body wall nerve was stimulated, producing a pattern of discharges that lasts about a minute. DSI bursts alternate with VSI bursts producing dorsal and ventral body flexions. To the right is the neural circuit from sensory neurons to efferent output.

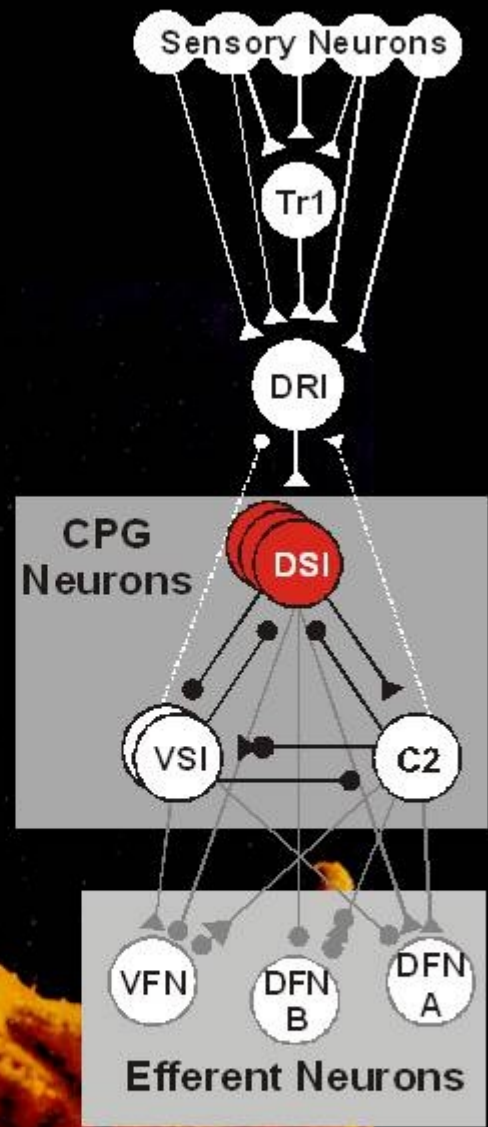
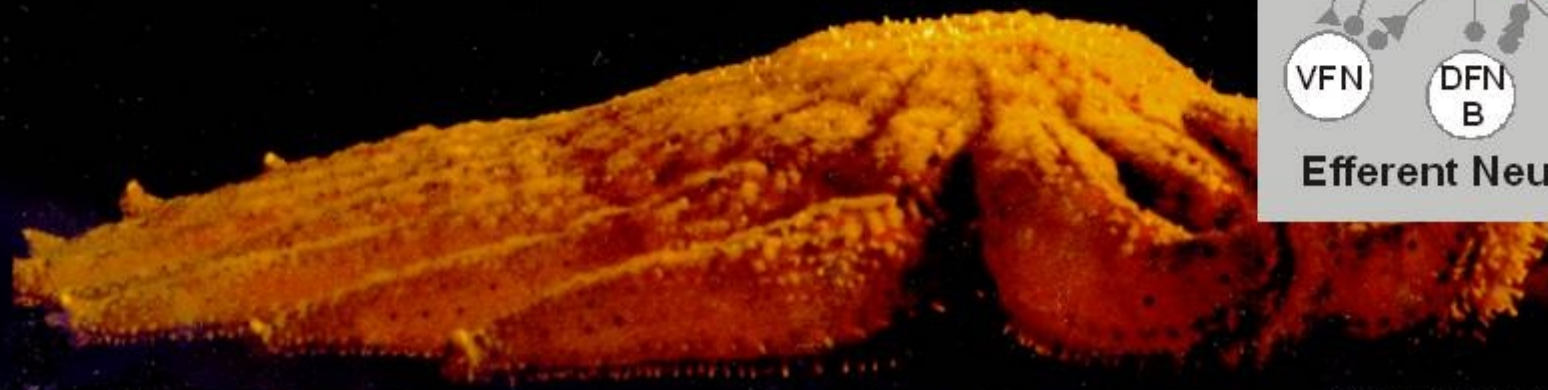
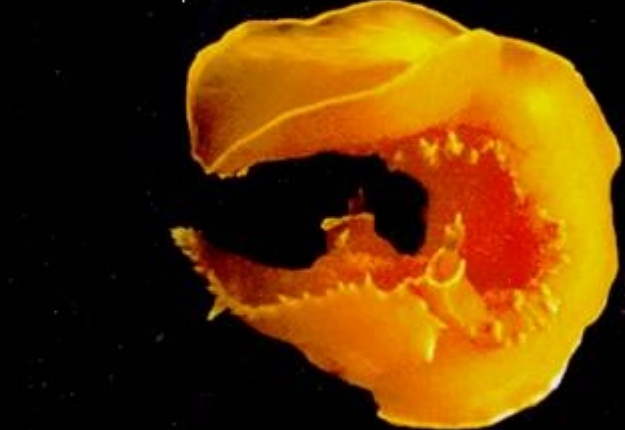
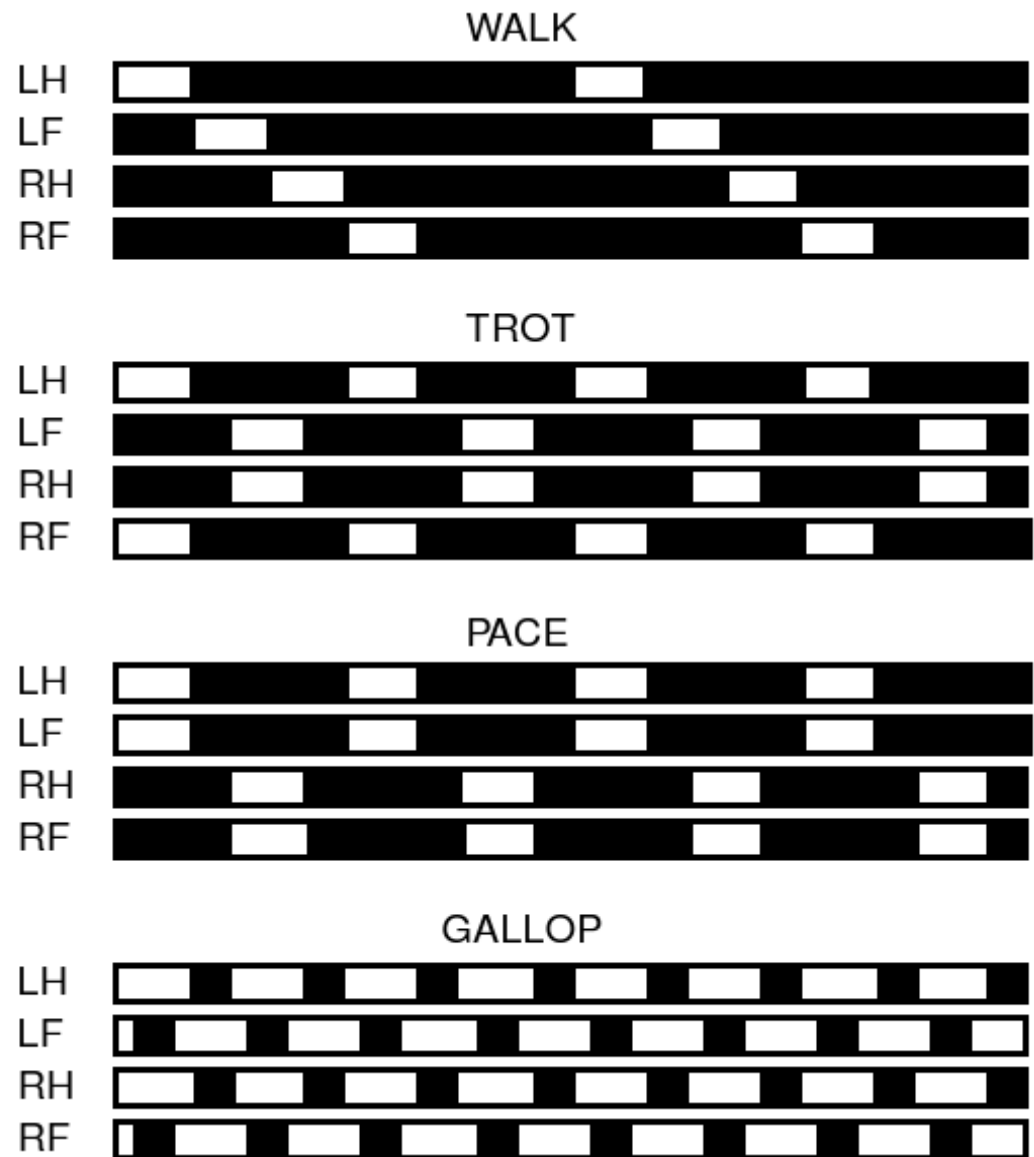
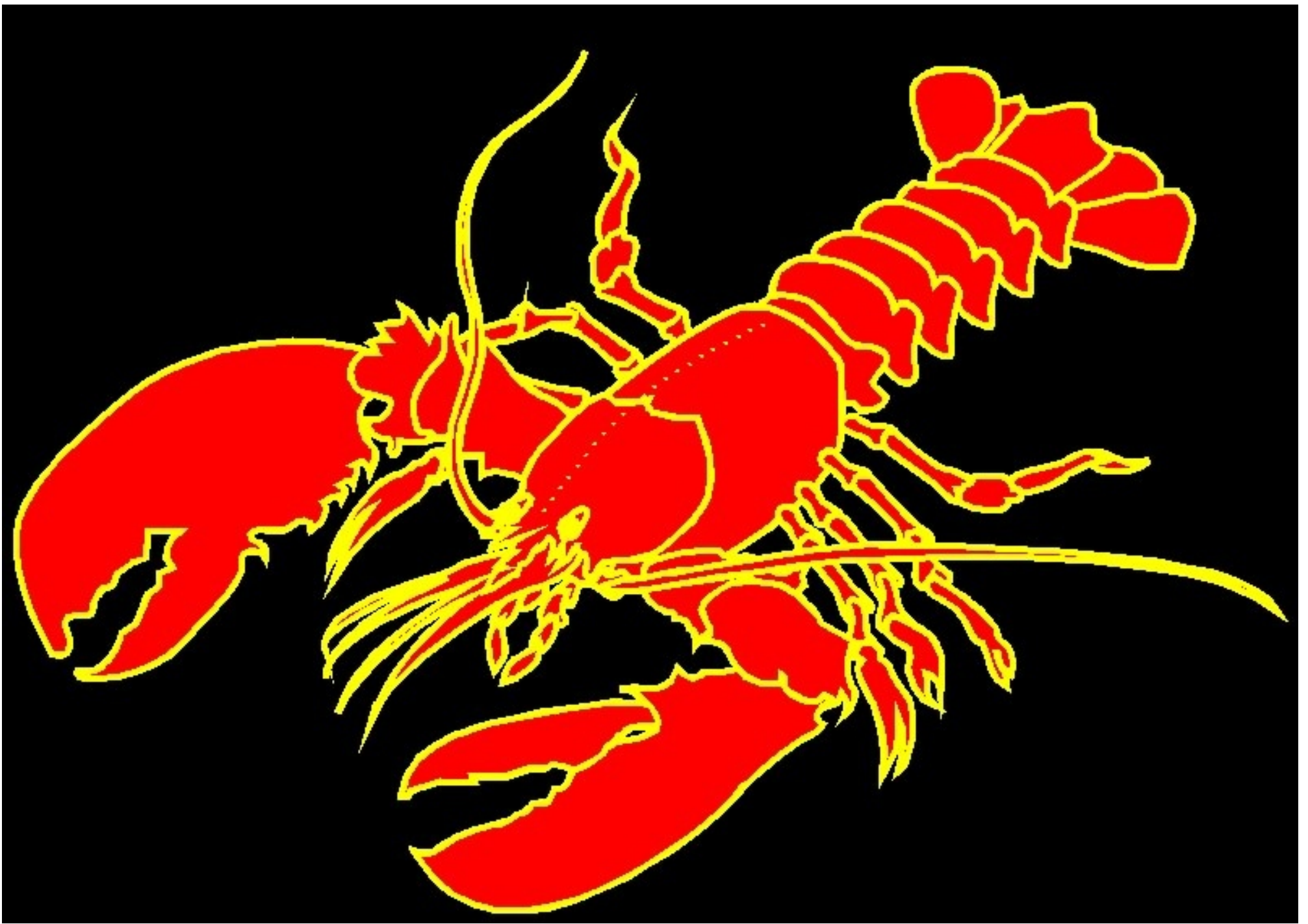


Photo by Bill Frost

- Ośrodkowe generatory wzorców – obwody nerwowe odpowiedzialne za generację rytmicznych ruchów mięśni
- Generują oscylacje nawet przy braku wejścia
- Łatwa adaptacja ruchów oscylacyjnych do zmiennych warunków wykazuje, że wejście sensoryczne moduluje aktywność CPG
- CPG mogą się przełączać między różnymi wzorcami aktywności pod wpływem bodźców zewnętrznych i kontroli z wyższych centrów UN, dlatego możemy je traktować jako jedną część rozproszonego układu sterowania

- Wiele CPG potrafi generować rytmy o różnym charakterze, np. spacer, trucht, jednochód, galop







Przykład: stomatogastric ganglion

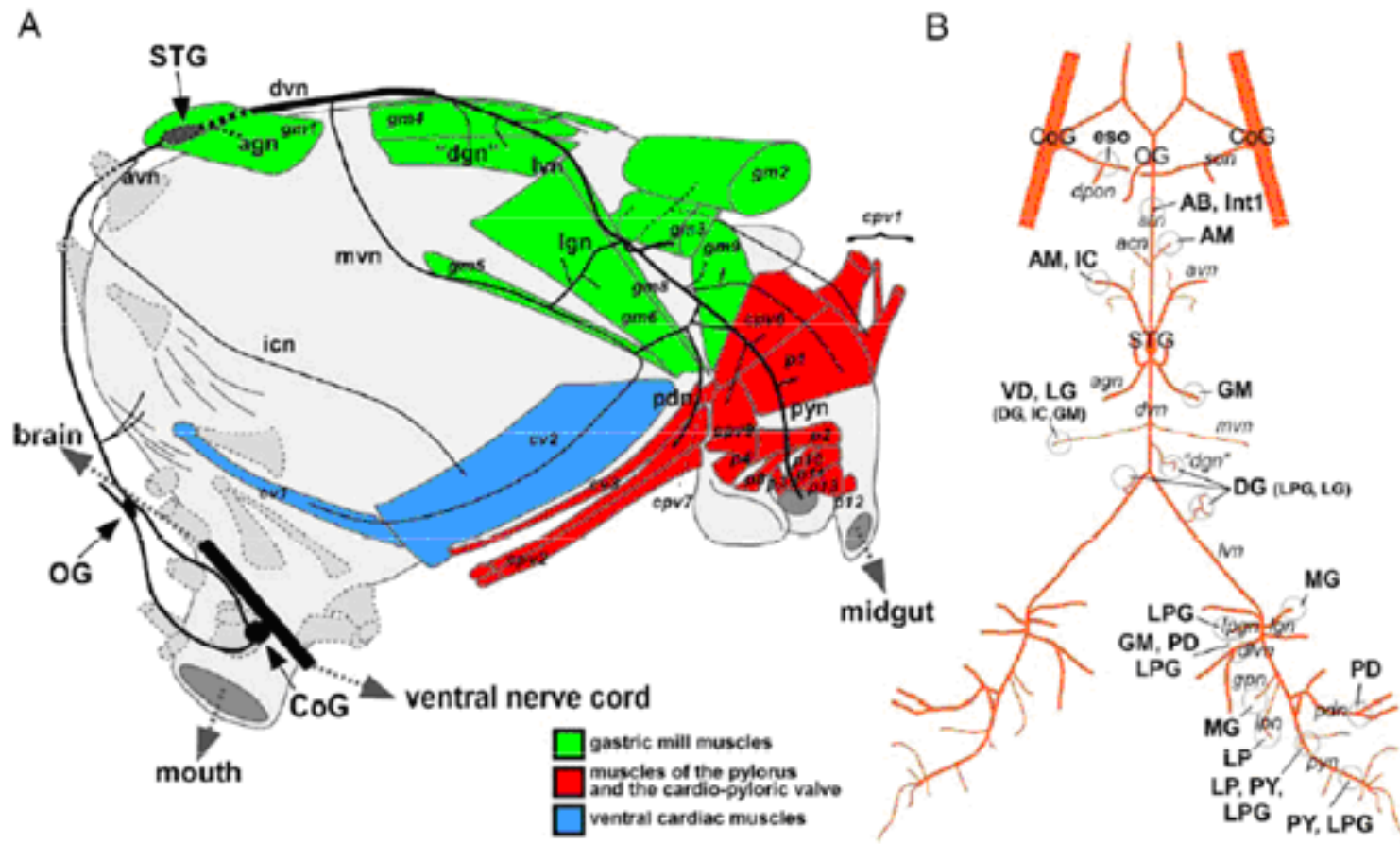


Figure 1: The muscles and nerves of the stomatogastric system. A. Muscles shown in green control the "teeth" of the gastric mill, those in red the pyloric region and blue, part of the cardiac sac. B. Nerves containing the axons of the neurons within the stomatogastric ganglion. Adapted from Heinzl and Boehm (unpublished).

Pyloric CPG

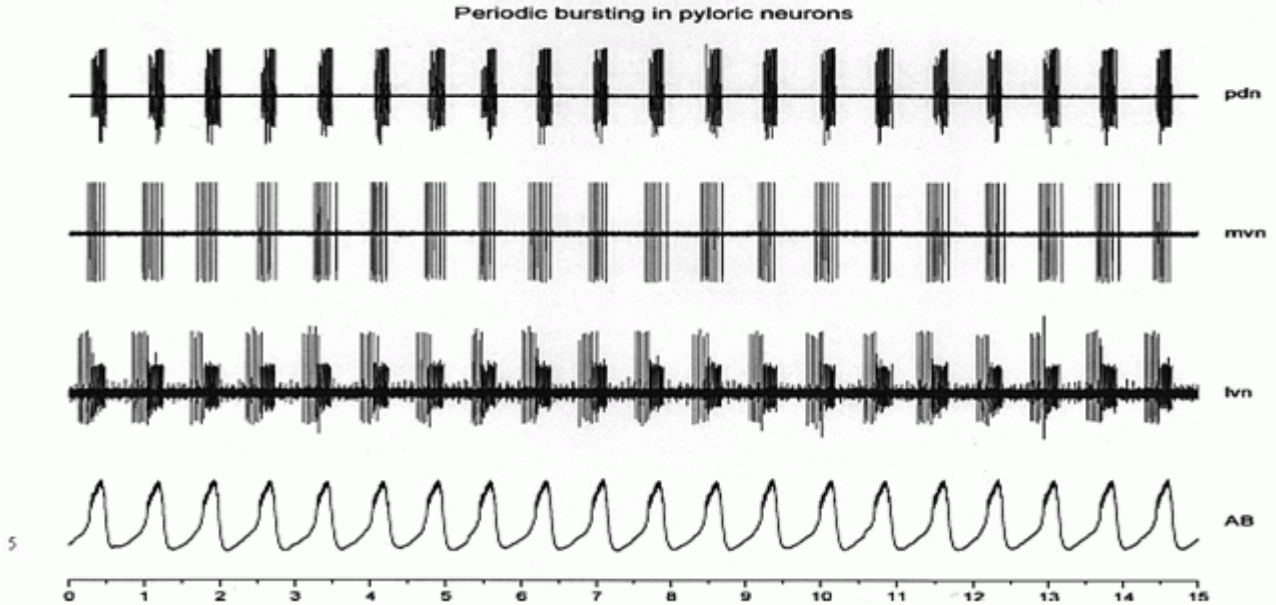
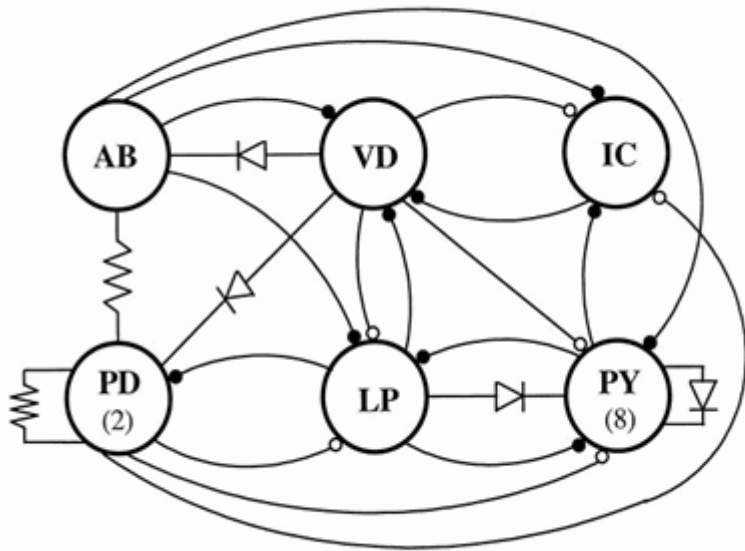


Figure 5: Simplified version of the pyloric circuit and extracellular recordings of the in vitro motor pattern. Black dots represent glutamatergic inhibitory synapses and open circles cholinergic inhibitory synapses. Resistors indicate electrical connections and diodes are rectifying connections. The motor pattern at right shows the two PD axons in the pdn, VD in the mvn, LP (large spike), PD and some PY units in the lvn. The intracellular recording is from the AB interneuron.

Pyloric Neurons

# of copies	Name	Abbr.	Muscle	Transmitter
1	anterior burster	(AB)	interneuron	glu
2	pyloric dilator	(PD)	cpv 1&2	ach
1	lateral pyloric	(LP)	p1	glu
1	ventricular dilator	(VD)	cv 2	ach
1	inferior cardiac	(IC)	cv 3	glu
8	pyloric	(PY)	p 2-4, 7-8, 10-11	glu

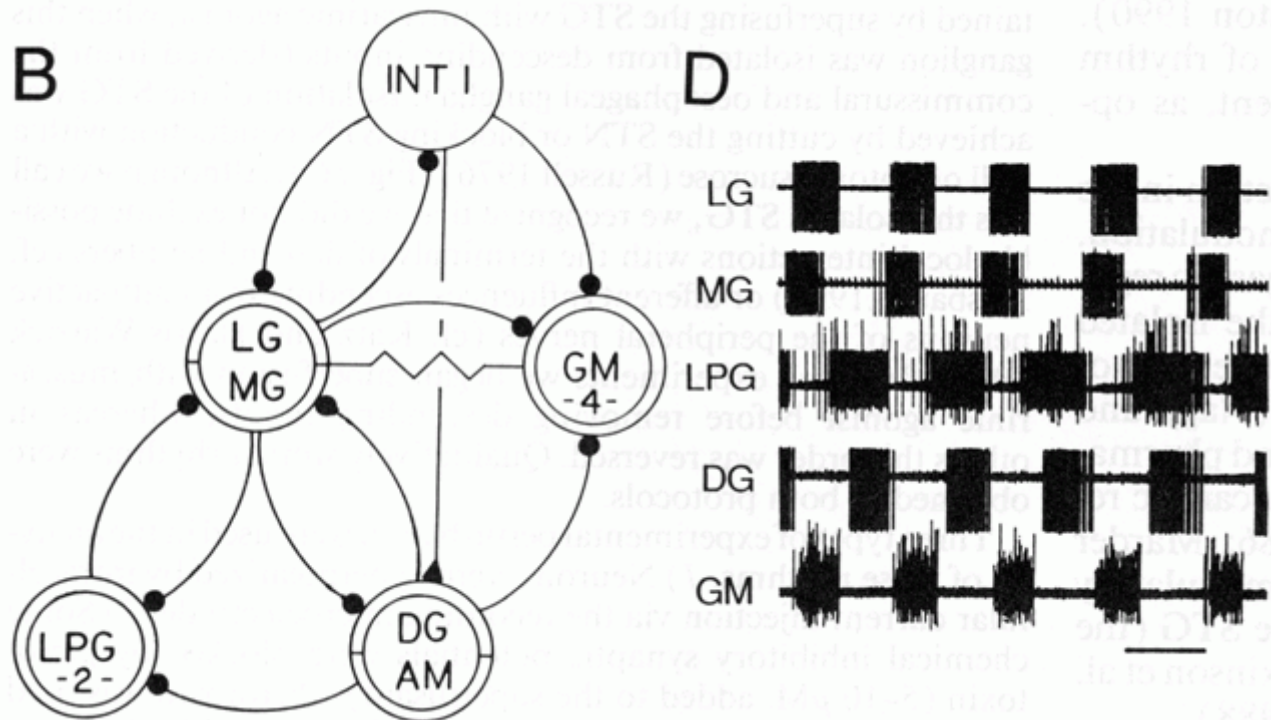
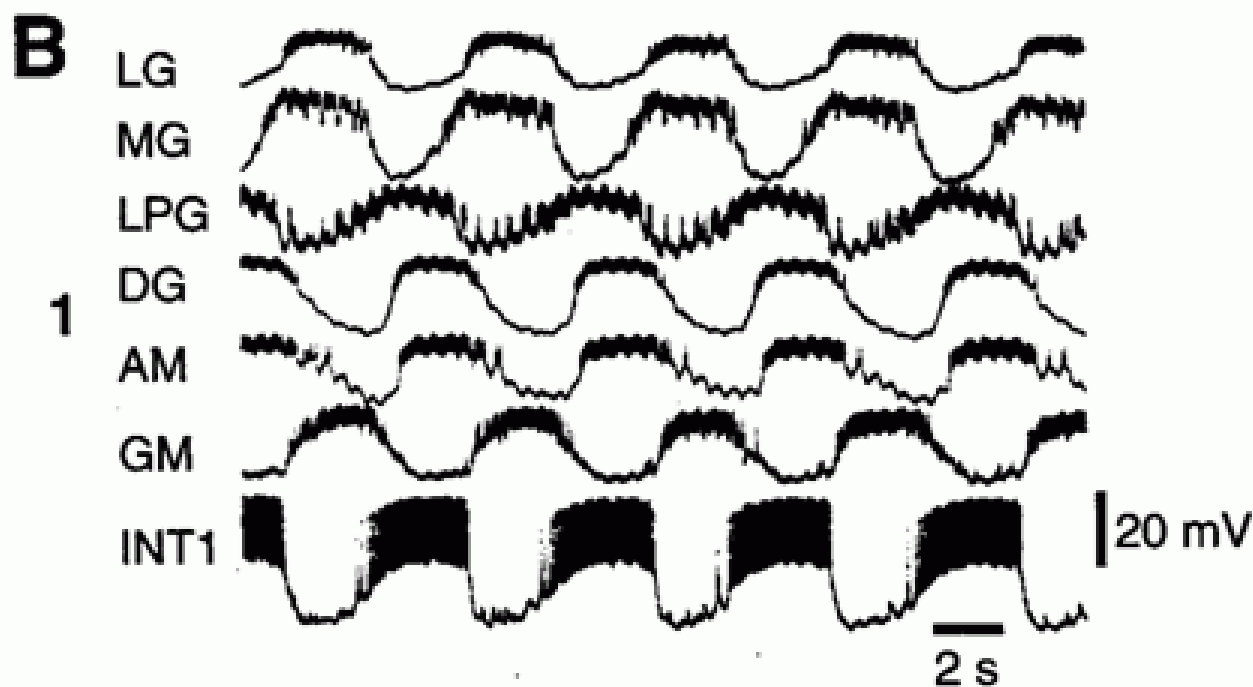
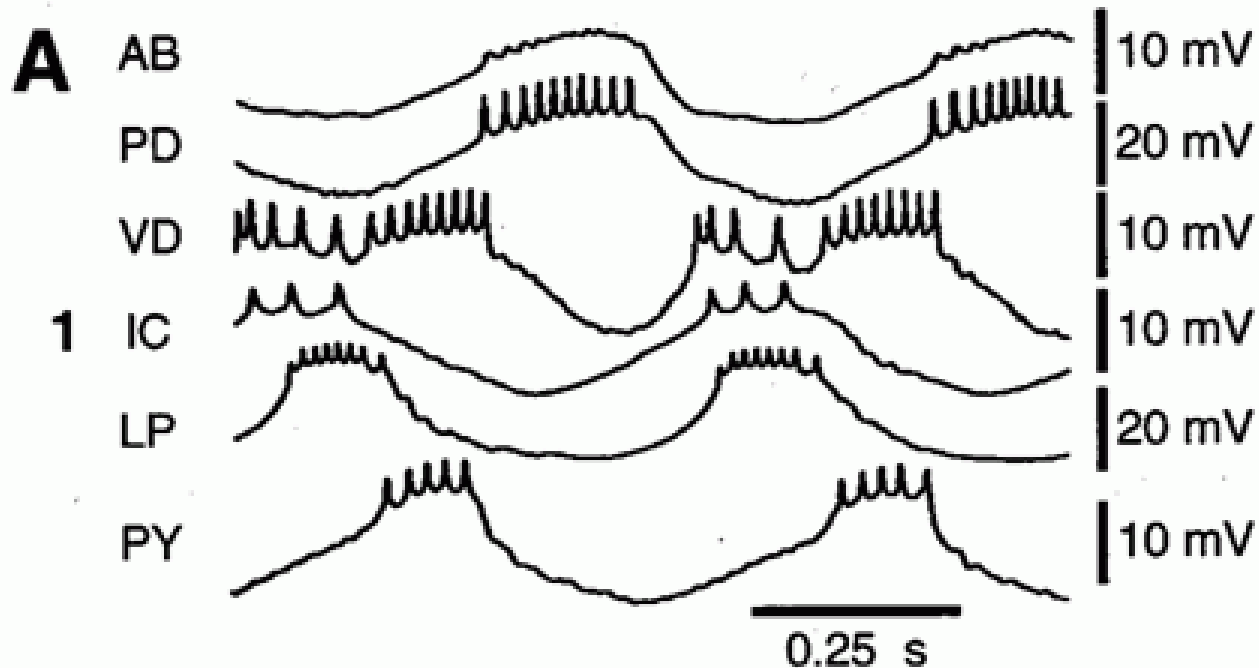


Figure 6: B. Simplified gastric mill circuit and in vitro motor pattern. The symbols are as in Fig.5 except the transmitters are not coded and the triangle from Int 1 is excitatory. D. The motor pattern shown here has five phases. Time bar ca 3 sec. The AM neuron is not shown.

Gastric Mill Neurons

# of copies	Name	Abbr.	Muscle	Transmitter
1	Interneuron 1	(Int 1)	interneuron	glu
4	Gastric Mill	(GM)	gm 1b,2a,b	ach
1	Dorsal Gastric	(DG)	gm 4a,b,c	ach
1	Anterior Median	(AM)	c 6, c7	glu
1	Lateral Gastric	(LG)	gm 5b, 6a	glu
1	Medial Gastric	(MG)	gm 9a, 9c	glu
2	Lateral Posterior Gastric	(LPG)	gm 3	ach

Figure 7: A. Simultaneous intracellular recordings from all neuron types in the pyloric CPG. B. Simultaneous intracellular recordings from gastric mill neurons. Recordings in A made by J.P. Miller and in B by H.G. Heinzel.



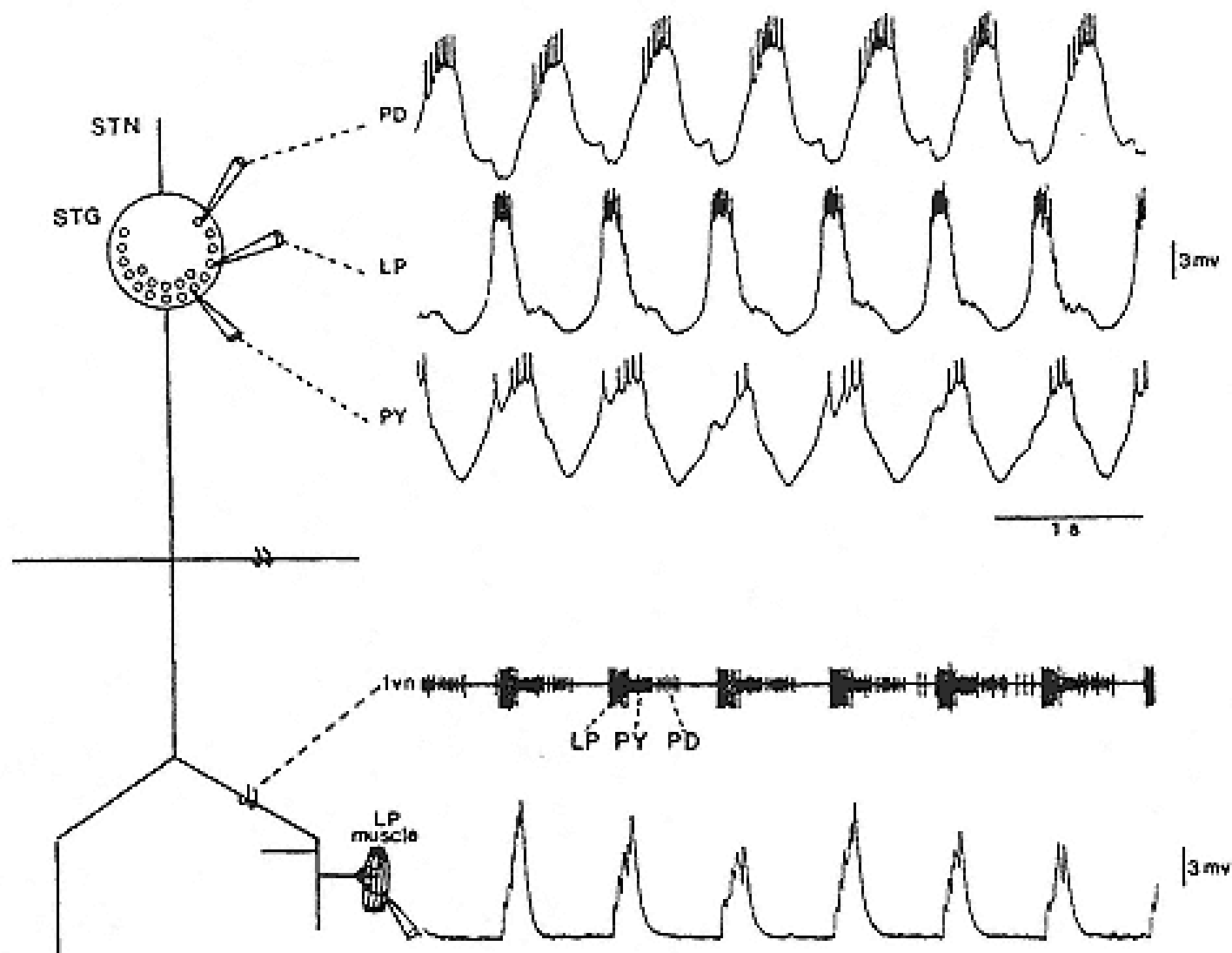


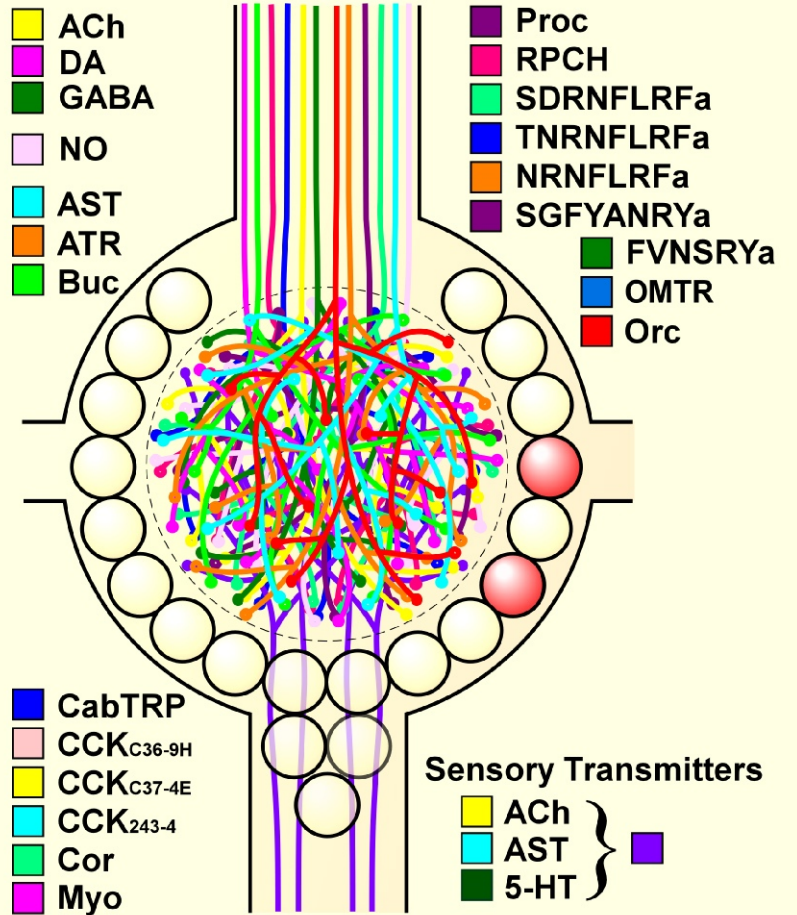
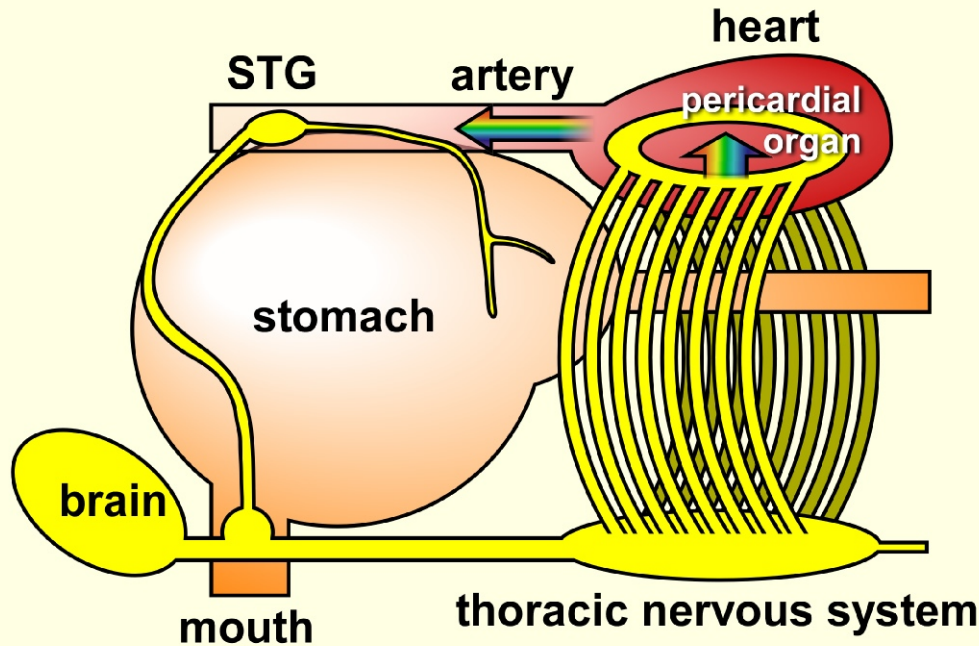
Figure 1: The pyloric rhythm. The stick figure shows the positions of the recordings shown on the right. All recordings were simultaneous. The top three traces are intracellular recordings from the somata of the PD, LP and PY neurons, the next trace is an extracellular recording from the *lvn* and the bottom trace is an intracellular recording from one of the muscles innervated by the LP neuron. Modified from Marder et al. (1987).

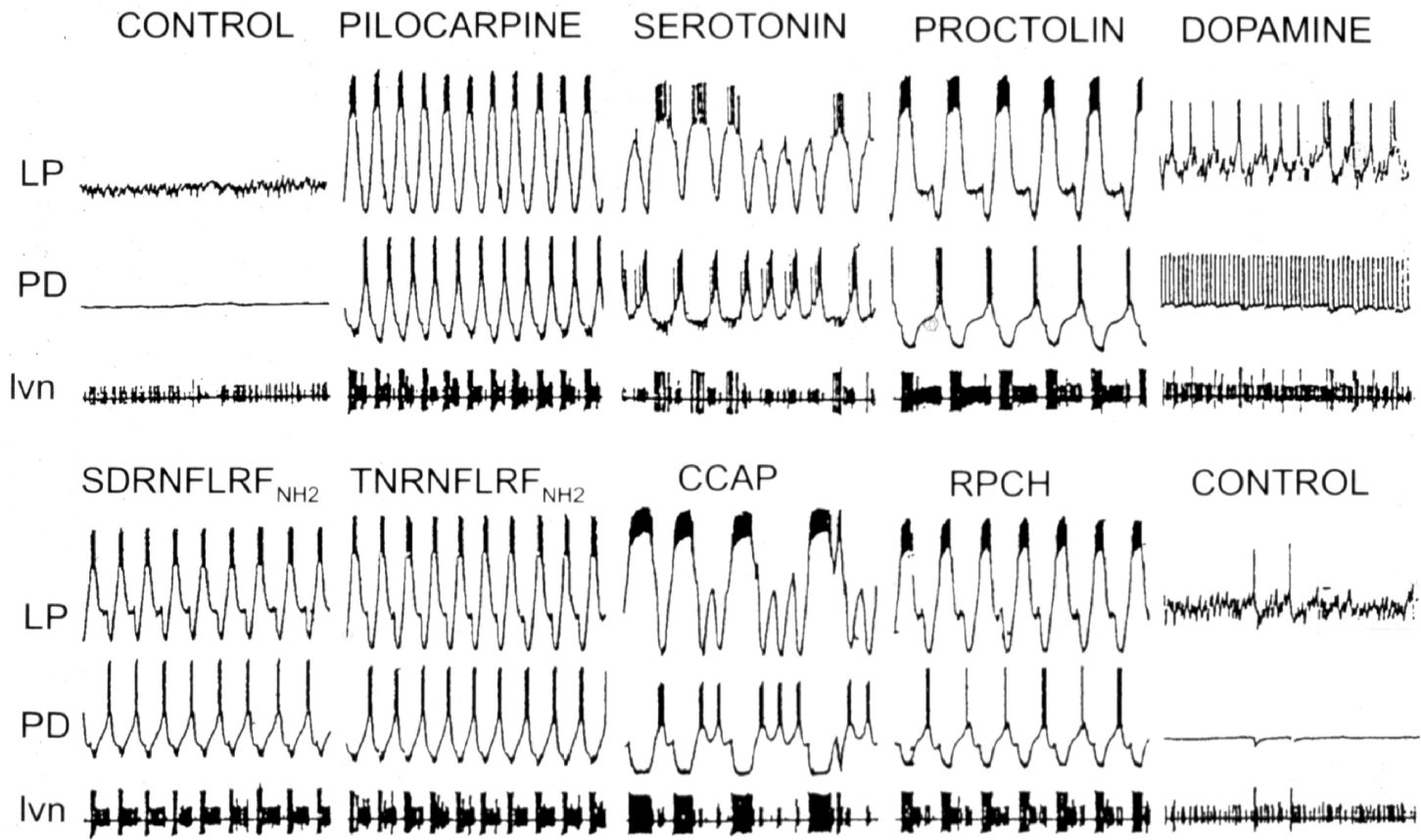
circulating neurohormones

locally-delivered neuromodulators

- | | | | |
|--------|------|-----------------------|-----------|
| DA | CCAP | β -PDH | SGFYANRYa |
| 5-HT | RPCH | CCK _{C36-9H} | FVNSRYa |
| AST | Cor | CCK ₂₄₃₋₄ | PAFYSQRYa |
| ATR | Proc | SDRNFLRFa | Cor2 |
| Buc | Myo | TNRNFLRFa | Pevkinin |
| CabTRP | Orc | NRNFLRFa | OMTR |

- | | |
|------|-----------|
| ACh | Proc |
| DA | RPCH |
| GABA | SDRNFLRFa |
| NO | TNRNFLRFa |
| AST | NRNFLRFa |
| ATR | SGFYANRYa |
| Buc | FVNSRYa |
| | OMTR |
| | Orc |
-
- | | |
|-----------------------|----------------------|
| CabTRP | Sensory Transmitters |
| CCK _{C36-9H} | |
| CCK _{C37-4E} | |
| CCK ₂₄₃₋₄ | |
| Cor | |
| Myo | ACh |
| | AST |
| | 5-HT |





$$\dot{\theta}_i(t) = \omega_i$$

$$\dot{\theta}_1(t) = \omega_1 + h_{12}(\theta_1, \theta_2)$$

$$\dot{\theta}_2(t) = \omega_2 + h_{21}(\theta_2, \theta_1),$$

$$\phi(t) = \theta_1(t) - \theta_2(t)$$

$$\begin{aligned}\dot{\phi}(t) &= \dot{\theta}_1(t) - \dot{\theta}_2(t) \\ &= (\omega_1 - \omega_2) + (h_{12}(\theta_1, \theta_2) - h_{21}(\theta_2, \theta_1))\end{aligned}$$

$$\dot{\phi}(t) = (\omega_1 - \omega_2) - (a_{12} + a_{21}) \sin(\phi(t))$$

$$\dot{\phi}(t) = (\omega_1 - \omega_2) - (a_{12} + a_{21}) \sin(\phi(t))$$

$$\phi = \arcsin\left(\frac{\omega_1 - \omega_2}{a_{12} + a_{21}}\right)$$

$$\dot{\theta}_1(t) = \omega_1 + h_{12}(\theta_1, \theta_2)$$

$$\dot{\theta}_2(t) = \omega_2 + h_{21}(\theta_2, \theta_1) + h_{23}(\theta_2, \theta_3)$$

$$\dot{\theta}_3(t) = \omega_3 + h_{32}(\theta_3, \theta_2) + h_{34}(\theta_3, \theta_4)$$

$$\dot{\theta}_4(t) = \omega_4 + h_{43}(\theta_4, \theta_3).$$

$$\phi_i(t) = \theta_i(t) - \theta_{i+1}(t)$$

$$\dot{\phi}(t) = \Omega + AS(t)$$

$$\phi(t) = \begin{bmatrix} \phi_1(t) \\ \phi_2(t) \\ \phi_3(t) \end{bmatrix} \quad A = a \begin{bmatrix} -2 & 1 & 0 \\ 1 & -2 & 1 \\ 0 & 1 & -2 \end{bmatrix}$$

$$\Omega = \begin{bmatrix} \omega_1 - \omega_2 \\ \omega_2 - \omega_3 \\ \omega_3 - \omega_4 \end{bmatrix} \quad S = \begin{bmatrix} \sin(\phi_1(t)) \\ \sin(\phi_2(t)) \\ \sin(\phi_3(t)) \end{bmatrix}$$

$\dot{\phi} = 0$ when $S = -A^{-1}\Omega$, and we know that

$$A^{-1} = \frac{-1}{4a} \begin{bmatrix} 3 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 3 \end{bmatrix}$$

If we assume that there is a smooth gradient in the intrinsic frequency of oscillation along the cord, then the frequency difference along the chain is constant, and $\omega_1 - \omega_2 = \omega_2 - \omega_3 = \omega_3 - \omega_4 = c$. In this case,

$$\Omega = c \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \quad S = \frac{c}{2a} \begin{bmatrix} 3 \\ 4 \\ 3 \end{bmatrix} \quad \left| \frac{c}{a} \right| \leq \frac{1}{2}$$